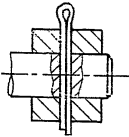
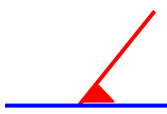
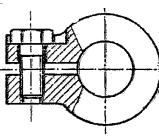
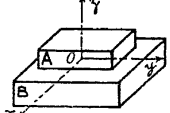
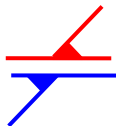
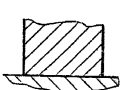
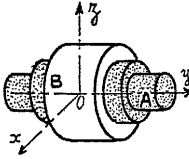
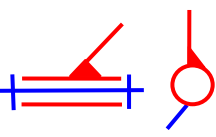
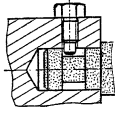
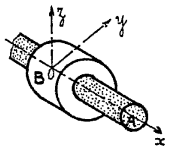
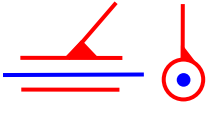
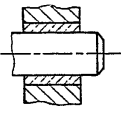
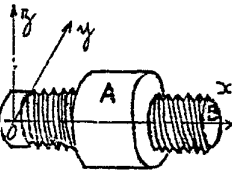
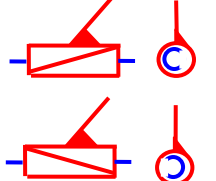
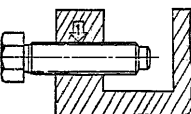
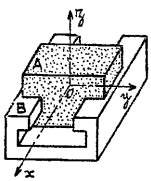
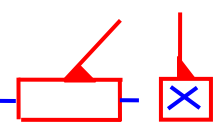
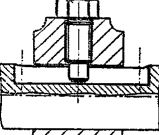
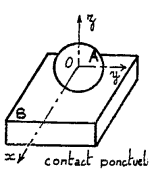
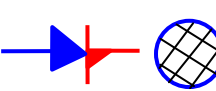
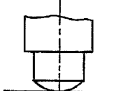
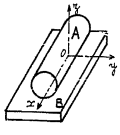
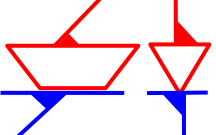
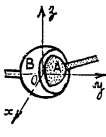
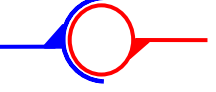
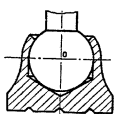
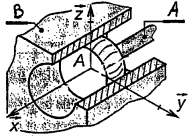


Nom de la liaison	Modèle théorique	Mouvements de A/B et degrés de liberté	Représentation plane	Ex de modèle technologique
Liaison encastrement		0 T (Translation) 0 R (Rotation) ddl = 0		
Liaison appui plan		2 T 1 R ddl = 3		
Liaison pivot		0 T 1 R ddl = 1		
Liaison Pivot glissant		1 T 1 R ddl = 2		
Liaison hélicoïdale		1 T et 1 R conjuguées ddl = 1		
Liaison glissière		1 T 0 R ddl = 1		
Liaison ponctuelle		2 T 3 R ddl = 5		
Liaison rectiligne		2 T 2 R ddl = 4		
Liaison rotule		0 T 3 R ddl = 3		
Liaison linéaire annulaire		1 T 3 R ddl = 4	