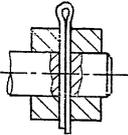
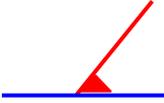
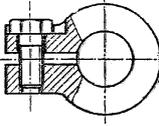
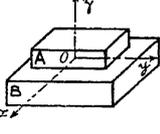
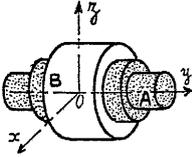
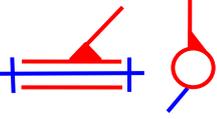
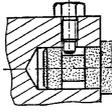
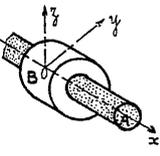
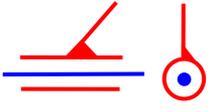
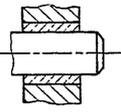
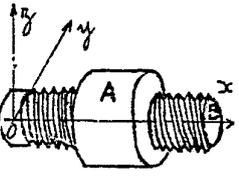
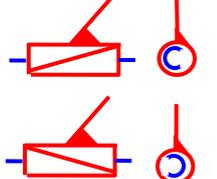
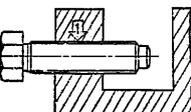
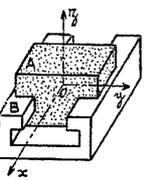
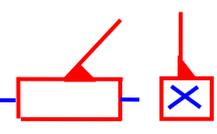
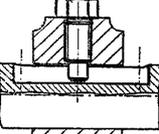
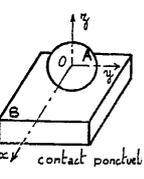
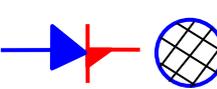
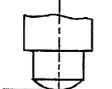
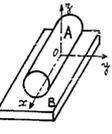
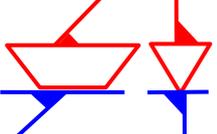
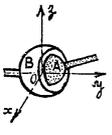
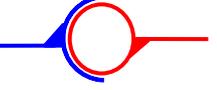
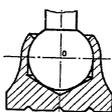
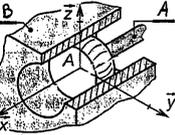


Nom de la liaison	Modèle théorique	Mouvements de A/B et degrés de liberté	Représentation plane	Ex de modèle technologique
Liaison encastrement		<b>0 T (Translation)</b> <b>0 R (Rotation)</b> <b>ddl = 0</b>		
Liaison appui plan		<b>2 T</b> <b>1 R</b> <b>ddl = 3</b>		
Liaison pivot		<b>0 T</b> <b>1 R</b> <b>ddl = 1</b>		
Liaison Pivot glissant		<b>1 T</b> <b>1 R</b> <b>ddl = 2</b>		
Liaison hélicoïdale		<b>1 T</b> <b>et 1 R conjuguées</b> <b>ddl = 1</b>		
Liaison glissière		<b>1 T</b> <b>0 R</b> <b>ddl = 1</b>		
Liaison ponctuelle		<b>2 T</b> <b>3 R</b> <b>ddl = 5</b>		
Liaison rectiligne		<b>2 T</b> <b>2 R</b> <b>ddl = 4</b>		
Liaison rotule		<b>0 T</b> <b>3 R</b> <b>ddl = 3</b>		
Liaison linéaire annulaire		<b>1 T</b> <b>3 R</b> <b>ddl = 4</b>	